Chapter 11 APPROXIMATIONS FOR ANALOG FILTERS

11.1 Introduction, 11.2 Basic Concepts
11.3-11.7 Butterworth, Chebyshev, Inverse-Chebyshev,
Elliptic, and Bessel-Thomson Approximations

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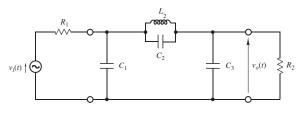
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- This presentation deals with the basics of these approximations.



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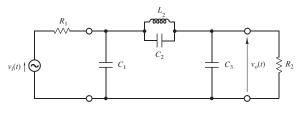


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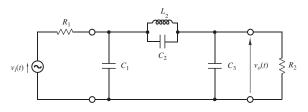
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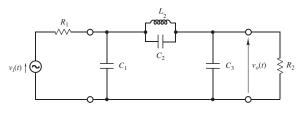
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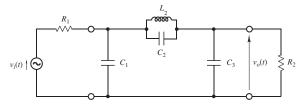
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- -H(s) is the transfer function,
- N(s) and D(s) are polynomials in complex variable s.



• The loss (or attenuation) is defined as

$$L(\omega^2) = \frac{|V_i(j\omega)|^2}{|V_o(j\omega)|^2} = \left|\frac{V_i(j\omega)}{V_o(j\omega)}\right|^2 = \frac{1}{|H(j\omega)|^2} = 10\log\frac{1}{H(j\omega)H(-j\omega)}$$

Hence the loss in dB is given by

$$A(\omega) = 10 \log L(\omega^2) = 10 \log \frac{1}{|H(j\omega)|^2}$$
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• As a function of ω , $A(\omega)$ is said to be the *loss characteristic*.

• The phase shift and group delay of analog filters are defined just as in digital filters, namely, the phase shift is the phase angle of the frequency response and the group delay is the negative of the derivative of the phase angle with respect to ω , i.e.,

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$$\theta(\omega) = \arg H(j\omega)$$
 and $\tau(\omega) = -\frac{d\theta(\omega)}{d\omega}$

• As functions of ω , $\theta(\omega)$ and $\tau(\omega)$ are the *phase response* and *delay characteristic*, respectively.

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 Thus if the transfer function of an analog filter is known, its loss function can be readily deduced.

If

$$H(s) = \frac{N(s)}{D(s)} = \frac{\prod_{i=1}^{M} (s - z_i)}{\prod_{i=1}^{N} (s - p_i)}$$

then

$$L(-s^{2}) = \frac{D(s)D(-s)}{N(s)N(-s)} = \frac{\prod_{i=1}^{N}(s-p_{i})\prod_{i=1}^{N}(-s-p_{i})}{\prod_{i=1}^{M}(s-z_{i})\prod_{i=1}^{M}(-s-z_{i})}$$
$$= (-1)^{N-M} \frac{\prod_{i=1}^{N}(s-p_{i})\prod_{i=1}^{N}[s-(-p_{i})]}{\prod_{i=1}^{M}(s-z_{i})\prod_{i=1}^{M}[s-(-z_{i})]}$$

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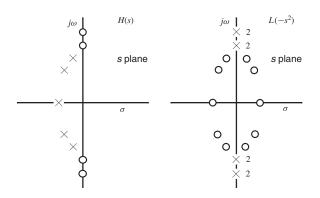
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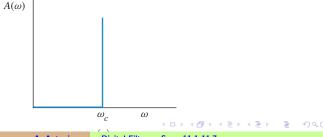
- Therefore,
 - the zeros of the loss function are the poles of the transfer function and their negatives, and
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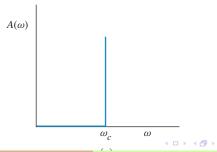
• Zero-pole plots for transfer function and loss function:



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 - The frequency range 0 to ω_c is the *passband*.
 - The frequency range ω_c to ∞ is the *stopband*.
 - The boundary between the passband and stopband, namely, ω_c , is the *cutoff frequency*.



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- In the classical solutions of the approximation problem, an ideal *normalized* lowpass loss characteristic is assumed with a cutoff frequency of order unity, i.e., $\omega_c \approx 1$.
- A set of formulas are then derived that yield the zeros and poles or coefficients of the transfer function for a specified filter order.

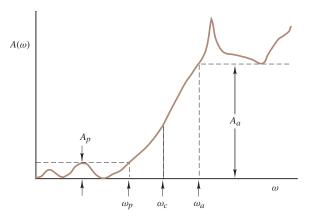
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 - the loss is equal to or greater than A_a dB over the frequency range ω_a to ∞ .
- Parameters ω_p and ω_a are the *passband* and *stopband* edges, A_p is the *maximum passband loss* (or *attenuation*), and A_a is the *minimum stopband loss* (or *attenuation*), respectively.

• The quality of an approximation depends on the values of A_p and A_a for a given filter order, i.e., a lower A_p and a larger A_a correspond to a better filter.



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- These transformations will be discussed in the next presentation.

Realizability Constraints

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- The poles must be in the left half *s* plane.
 - Otherwise, the transfer function would represent an unstable system.



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 - Minimum filter order to achieve prescribed specifications.
 - Formulas for the parameters of the transfer function (e.g., zeros, poles, coefficients, multiplier constant).

• The Butterworth approximation is derived on the assumption that the loss function $L(-s^2)$ is a polynomial. Since

$$\lim_{s\to\infty} L(-s^2) = \lim_{\omega\to\infty} L(\omega^2) = a_0 + a_2\omega^2 + \dots + a_{2n}\omega^{2n} \to \infty$$

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This is achieved by letting

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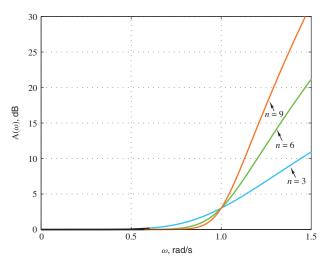
where $x=\omega^2$, i.e., n derivatives of the loss are set to zero at zero frequency.

• Assuming that L(1) = 2, the loss function in dB can be expressed as

$$L(\omega^2) = 1 + \omega^{2n}$$
 and $A(\omega) = 10 \log(1 + \omega^{2n})$



• Typical loss characteristics:



 The loss function for the normalized Butterworth approximation (3-dB frequency at 1 rad/s) is given by

$$L(-s^2) = 1 + (-s^2)^n = \prod_{i=1}^{2n} (s - z_i)$$

$$z_i = \begin{cases} e^{j(2i-1)\pi/2n} & \text{for even } n \\ e^{j(i-1)\pi/n} & \text{for odd } n \end{cases}$$

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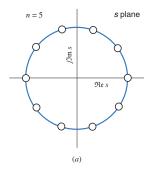
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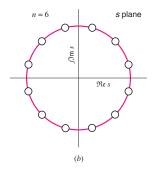
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where

• Since $|z_k| = 1$, the zeros of $L(-s^2)$ are located on the *unit circle* |s| = 1.

• Zero-pole plots for loss function:





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Therefore, they are identical with the zeros of the loss function located in the left-half s plane.

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The *minimum* filter order that will satisfy the required specifications must be large enough to satisfy *both* of the following inequalities:

$$n \geq rac{\left[-\log\left(10^{0.1A_p}-1
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(See textbook for derivations and examples.)

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 Once the required filter order is determined, the actual maximum passband loss and minimum stopband loss can be calculated as

$$A_p=A(\omega_p)=10\log(1+\omega_p^{2n})\quad\text{and}\quad A_a=A(\omega_a)=10\log(1+\omega_a^{2n})$$
 respectively.

Chebyshev Approximation

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 - On the other hand, the stopband loss is very small at frequencies close to the stopband edge and very large at very high frequencies.
- A more balanced characteristic with respect to the passband can be achieved by employing the *Chebyshev* approximation.

Chebyshev Approximation Cont'd

• As in the Butterworth approximation, the loss function in the Chebyshev approximation is assumed to be a polynomial in s, which would assure a lowpass characteristic.

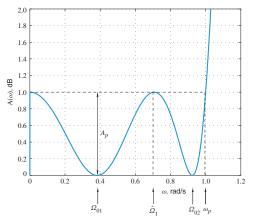
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On the basis of this assumption, a differential equation is constructed whose solution gives the zeros of the loss function.

- As in the Butterworth approximation, the loss function in the Chebyshev approximation is assumed to be a polynomial in s, which would assure a lowpass characteristic.
- The derivation of the Chebyshev approximation is based on the assumption that the passband loss oscillates between zero and a specified maximum loss A_p .
 - On the basis of this assumption, a differential equation is constructed whose solution gives the zeros of the loss function.
- Then by neglecting the zeros of the loss function in the right-half s plane, the poles of the transfer function can be obtained.

• In the case of a fourth-order Chebyshev filter the passband loss is assumed to be zero at $\omega=\Omega_{01},\,\Omega_{02}$ and equal to A_p at $\omega=0,\,\hat{\Omega}_1,\,1$ as shown in the figure:



 On using all the information that can be extracted from the figure shown, a differential equation of the form

$$\left[\frac{dF(\omega)}{d\omega}\right]^2 = \frac{M_4[1 - F^2(\omega)]}{1 - \omega^2}$$

can be constructed.

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The solution of this differential equation gives the loss as

$$L(\omega^2)=1+\varepsilon^2F^2(\omega)$$
 where
$$\varepsilon^2=10^{0.1A_p}-1$$
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 $\varepsilon^2 = 10^{0.1A_p} - 1$ $F(\omega) = T_4(\omega) = \cos(4\cos^{-1}\omega)$

• The function $\cos(4\cos^{-1}\omega)$ is actually a polynomial known as the *4th-order Chebyshev* polynomial.



where

and

 Similarly, for an nth-order Chebyshev approximation, one can show that

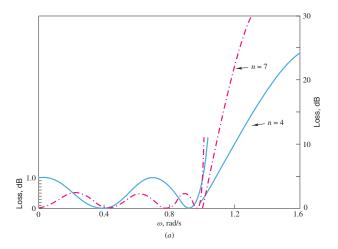
$$A(\omega) = 10 \log L(\omega^2) = 10 \log[1 + \varepsilon^2 T_n^2(\omega)]$$

where
$$\varepsilon^2 = 10^{0.1A_p} - 1$$

and
$$T_n(\omega) = egin{cases} \cos(n\cos^{-1}\omega) & ext{ for } |\omega| \leq 1 \ \cosh(n\cosh^{-1}\omega) & ext{ for } |\omega| > 1 \end{cases}$$

is the *nth-order* Chebyshev polynomial.

• Typical loss characteristics for Chebyshev approximation:



• The zeros of the loss function for a *normalized n*th-order Chebyshev approximation ($\omega_p = 1 \text{ rad/s}$) are given by $s_i = \sigma_i + j\omega_i$ where

$$\sigma_{i} = \pm \sinh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\sin\frac{(2i-1)\pi}{2n}$$

$$\omega_{i} = \cosh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\cos\frac{(2i-1)\pi}{2n}$$

for i = 1, 2, ..., n.

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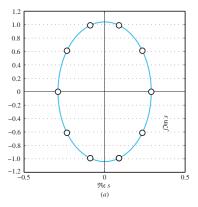
• From these equations, we note that

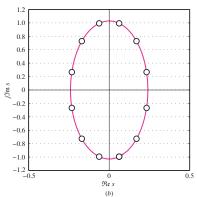
$$\frac{\sigma_i^2}{\sinh^2 u} + \frac{\omega_i^2}{\cosh^2 u} = 1 \quad \text{where} \quad u = \frac{1}{n} \sinh^{-1} \frac{1}{\varepsilon}$$

i.e., the zeros of $L(-s^2)$ are located on an *ellipse*.



• Typical zero-pole plots for Chebyshev approximation: (a) n = 5 $A_p = 1$ dB; (b) n = 6 $A_p = 1$ dB.





• An *n*th-order normalized Chebyshev transfer function with a passband edge $\omega_p=1$ rad/s and a maximum passband loss of A_p dB can be determined as follows:

$$H_N(s) = \frac{H_0}{D_0(s) \prod_i^r (s - p_i)(s - p_i^*)}$$

$$= \frac{H_0}{D_0(s) \prod_i^r [s^2 - 2\text{Re } (p_i)s + |p_i|^2]}$$

where

$$r = egin{cases} rac{n-1}{2} & ext{ for odd } n \ rac{n}{2} & ext{ for even } n \end{cases}$$
 and $D_0(s) = egin{cases} s-p_0 & ext{ for odd } n \ 1 & ext{ for even } n \end{cases}$

• The poles and multiplier constant, H_0 , can be calculated by using the following formulas in sequence:

$$\begin{split} \varepsilon &= \sqrt{10^{0.1A_p}-1} \\ p_0 &= \sigma_{(n+1)/2} \quad \text{with} \quad \sigma_{(n+1)/2} = -\sinh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right) \\ p_i &= \sigma_i + j\omega_i \qquad \text{for} \quad i=1,\,2,\,\ldots,\,r \\ \quad \text{where} \quad \sigma_i &= -\sinh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\sin\frac{(2i-1)\pi}{2n} \\ \omega_i &= \cosh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\cos\frac{(2i-1)\pi}{2n} \\ H_0 &= \begin{cases} -p_0\prod_{i=1}^r|p_i|^2 & \text{for odd } n \\ 10^{-0.05A_p}\prod_{i=1}^r|p_i|^2 & \text{for even } n \end{cases} \end{split}$$

• The minimum filter order required to achieve a maximum passband loss of A_p and a minimum stopband loss of A_a must be large enough to satisfy the inequality

$$n \geq \frac{\cosh^{-1}\sqrt{D}}{\cosh^{-1}\omega_a}$$
 where $D = \frac{10^{0.1A_a}-1}{10^{0.1A_p}-1}$

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The actual minimum stopband loss can be calculated as

$$A_a = A(\omega_a) = 10 \log L(\omega_a^2) = 10 \log[1 + \varepsilon^2 T_n^2(\omega_a)]$$



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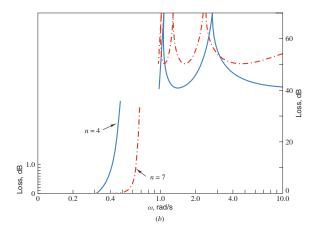
Inverse-Chebyshev Approximation

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Inverse-Chebyshev Approximation

- The inverse-Chebyshev approximation is closely related to the Chebyshev approximation, as may be expected, and it is actually derived from the Chebyshev approximation.
- The passband loss in the inverse-Chebyshev is very similar to that of the Butterworth approximation, i.e., it is an increasing monotonic function of ω , while the stopband loss oscillates between infinity and a prescribed minimum loss A_a .

Typical loss characteristics for inverse-Chebyshev approximation:



The loss for the inverse-Chebyshev approximation is given by

$$A(\omega) = 10 \log \left[1 + \frac{1}{\delta^2 T_n^2(1/\omega)} \right]$$

where

$$\delta^2 = \frac{1}{10^{0.1A_a} - 1}$$

and the stopband extends from $\omega=1$ to $\infty.$

• The *normalized* transfer function for a specified order, n, stopband edge of $\omega_a = 1$ rad/s, and minimum stopband loss, A_a , is given by

$$H_N(s) = \frac{H_0}{D_0(s)} \prod_{i=1}^r \frac{(s-1/z_i)(s-1/z_i^*)}{(s-1/p_i)(s-1/p_i^*)}$$
$$= \frac{H_0}{D_0(s)} \prod_{i=1}^r \frac{s^2 + \frac{1}{|z_i|^2}}{s^2 - 2\text{Re}\left(\frac{1}{p_i}\right)s + \frac{1}{|p_i|^2}}$$

where

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• The parameters of the transfer function can be calculated by using the formulas in the next slide.



$$\delta = \frac{1}{\sqrt{10^{0.1A_a}-1}}, \quad z_i = j\cos\frac{(2i-1)\pi}{2n} \qquad \text{for } 1,2,\ldots,r$$

$$p_0 = \sigma_{(n+1)/2} \quad \text{with} \quad \sigma_{(n+1)/2} = -\sinh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\delta}\right)$$

$$p_i = \sigma_i + j\omega_i \qquad \text{for } 1,2,\ldots,r$$

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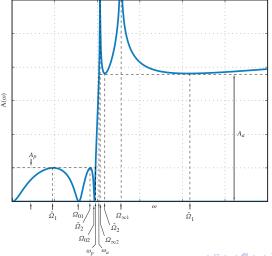
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In fact, this is the *optimal* approximation for a given piecewise constant approximation.

Elliptic Approximation Cont'd

Loss characteristic for a 5th-order elliptic approximation:



Elliptic Approximation Cont'd

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Elliptic Approximation Cont'd

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- After considerable mathematical complexity, the differential equation obtained is solved through the use of *elliptic* functions, and the parameters of the transfer function are deduced.

The approximation owes its name to the use of elliptic functions in the derivation.

 The passband and stopband edges and cutoff frequency of a normalized elliptic approximation are defined as follows:

$$\omega_p = \sqrt{k}, \quad \omega_a = \frac{1}{\sqrt{k}}, \quad \omega_c = \sqrt{\omega_a \omega_p} = 1$$

Constants k and k_1 given by

$$k = \frac{\omega_p}{\omega_a}$$
 and $k_1 = \left(\frac{10^{0.1A_p} - 1}{10^{0.1A_a} - 1}\right)^{1/2}$

are known as the *selectivity* and *discrimination* constants.

A normalized elliptic lowpass filter with a selectivity factor k, passband edge $\omega_p = \sqrt{k}$, stopband edge $\omega_a = 1/\sqrt{k}$, a maximum passband loss of A_p dB, and a minimum stopband loss equal to or in excess of A_a dB has a transfer function of the form

$$H_N(s) = \frac{H_0}{D_0(s)} \prod_{i=1}^r \frac{s^2 + a_{0i}}{s^2 + b_{1i}s + b_{0i}}$$
$$r = \begin{cases} \frac{n-1}{2} & \text{for odd } n \end{cases}$$

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 The parameters of the transfer function can be obtained by using the formulas in the next three slides in sequence in the order shown.

$$\begin{split} k' &= \sqrt{1-k^2} \\ q_0 &= \frac{1}{2} \left(\frac{1-\sqrt{k'}}{1+\sqrt{k'}} \right) \\ q &= q_0 + 2q_0^5 + 15q_0^9 + 150q_0^{13} \\ D &= \frac{10^{0.1A_s} - 1}{10^{0.1A_p} - 1} \\ n &\geq \frac{\log 16D}{\log(1/q)} \quad \text{(round up to the next integer)} \\ \Lambda &= \frac{1}{2n} \ln \frac{10^{0.05A_p} + 1}{10^{0.05A_p} - 1} \\ \sigma_0 &= \left| \frac{2q^{1/4} \sum_{m=0}^{\infty} (-1)^m q^{m(m+1)} \sinh[(2m+1)\Lambda]}{1 + 2\sum_{m=1}^{\infty} (-1)^m q^{m^2} \cosh 2m\Lambda} \right| \end{split}$$

$$W = \sqrt{\left(1 + k\sigma_0^2\right)\left(1 + \frac{\sigma_0^2}{k}\right)}$$

$$\Omega_i = \frac{2q^{1/4} \sum_{m=0}^{\infty} (-1)^m q^{m(m+1)} \sin \frac{(2m+1)\pi\mu}{n}}{1 + 2\sum_{m=1}^{\infty} (-1)^m q^{m^2} \cos \frac{2m\pi\mu}{n}}$$

where
$$\mu = \left\{ egin{array}{ll} i & ext{for odd } n \ i = 1, 2, \dots, r \ i - rac{1}{2} & ext{for even } n \end{array}
ight.$$

$$V_i = \sqrt{\left(1 - k\Omega_i^2\right)\left(1 - \frac{\Omega_i^2}{k}\right)}$$

$$egin{aligned} a_{0i} &= rac{1}{\Omega_i^2} \ b_{0i} &= rac{(\sigma_0 V_i)^2 + (\Omega_i W)^2}{\left(1 + \sigma_0^2 \Omega_i^2
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(See textbook for details.)



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 - In fact, it turns out to be highly nonlinear, as one might expect, particularly in the elliptic approximation.
- The last approximation in Chap. 11, namely, the Bessel-Thomson approximation, is derived on the assumption that the group delay is maximally flat at zero frequency.
- As in the Butterworth and Chebyshev approximations, the loss function is a polynomial. Hence the Bessel-Thomson approximation is essentially a *lowpass* approximation.

 The transfer function for a normalized Bessel-Thomson approximation is given by

$$H(s) = \frac{b_0}{\sum_{i=0}^{n} b_i s^i} = \frac{b_0}{s^n B(1/s)}$$

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• The group-delay is 1 s. An arbitrary delay can be obtained by replacing s by $\tau_0 s$ where τ_0 is a constant.

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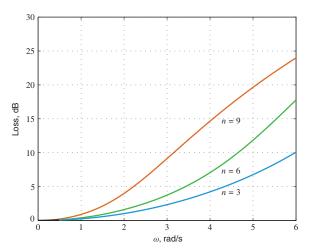
$$H(s) = \frac{b_0}{\sum_{i=0}^{n} b_i s^i} = \frac{b_0}{s^n B(1/s)}$$

where

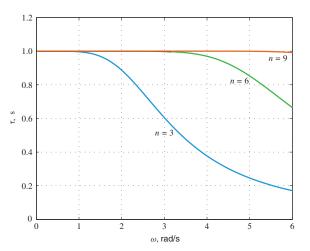
$$b_i = \frac{(2n-i)!}{2^{n-i}i!(n-i)!}$$

- The group-delay is 1 s. An arbitrary delay can be obtained by replacing s by $\tau_0 s$ where τ_0 is a constant.
- Function $B(\cdot)$ is a Bessel polynomial, and $s^nB(1/s)$ can be shown to have zeros in the left-half s plane, i.e., the Bessel-Thomson approximation represents stable analog filters.

• Typical loss characteristics:



• Typical delay characteristics:



This slide concludes the presentation.

Thank you for your attention.